## The Asynchronous Computability Theorem

A Marriage Between Distributed Systems and Algebraic Topology

> Hei Li

| 1999 | Peter Shor | for Shor's algorithm for factoring numbers in polynomial time on a <br> quantum computer |
| :--- | :--- | :--- |
| 2000 | Moshe Y. Vardi and Pierre Wolper | for work on temporal logic with finite automata |
| 2001 | Sanjeev Arora, Uriel Feige, Shafi Goldwasser, Carsten <br> Lund, László Lovász, Rajeev Motwani, Shmuel Safra, <br> Madhu Sudan, and Mario Szegedy | for the PCP theorem and its applications to hardness of <br> approximation |
| 2002 | Géraud Sénizergues | for proving that equivalence of deterministic pushdown automata is <br> decidable |
| 2003 | Yoav Freund and Robert Schapire | for the AdaBoost algorithm in machine learning |
| 2004 | Maurice Herlihy, Michael Saks, Nir Shavit and Fotios <br> Zaharoglou | for applications of topology to the theory of distributed computing |
| 2005 | Noga Alon, Yossi Matias and Mario Szegedy | for their foundational contribution to streaming algorithms |
| 2006 | Manindra Agrawal, Neeraj Kayal, Nitin Saxena | for the AKS primality test |
| 2007 | Alexander Razborov, Steven Rudich | for natural proofs |
| 2008 | Daniel Spielman, Shanghua Teng | for smoothed analysis of algorithms |
| 2009 | Omer Reingold, Salil Vadhan, Avi Wigderson | for zig-zag product of graphs and undirected connectivity in log <br> space |

Two nodes choose between 0 or $1 \rightarrow$ Come to agreement about one of their inputs

## Binary consensus problem in asynchronous wait-free model is unsolvable



No timing guarantees in execution
Nodes eventually halt with output value regardless of crashes in other nodes


Non-generalizable
No insights on properties of model of computation
Inelegant


Given: Number of heads and feet
Find: Number of chickens and rabbits


Given: 4 heads, 10 feet

Solution: 3 chickens
+1 rabbit




Given: 4 heads, 10 feet

No solutions - parallel lines

Step 2: Mathematics of the mathematical model

Solution for Animal count problem

Step 1: Relationship between concrete problem and some abstract model

Step 2: Mathematics of the abstract


A task : <l, O, $\Delta>$

A protocol solves* a task if given any starting input $x$ in I:
Final output is in $\Delta(x)$ *

For our binary consensus problem

$$
\begin{aligned}
& I=\{(0,0),(0,1),(1,0),(1,1)\}^{*} \\
& O=\{(0,0),(1,1)\}^{*} \\
& \Delta((0,1))=\{(0,0),(1,1)\}
\end{aligned}
$$

A protocol solves* a task if given any starting input x in I:

Final output is in $\Delta(x)$ *

$$
\Delta((1,1))=\ldots
$$

$$
\ldots\{(1,1)\}
$$

We need DIMENSION to represent clusters of nodes
Simplex is a set of mutually-connected vertices *
Complex is a collection of simplexes *

Simplex is a set of mutually-connected vertices *


Complex is a collection of simplexes *

Some simplices: $(1,2,3),(2,4),(3), \ldots$
The complex $(1,2,3,4)$ is formed by the basic simplices $(1,2,3)$ and $(2,3,4)$
$(1,2,3,4),(1,2,4)$ are not simplexes!

Given a complex C, a complex $\sigma(C)$ is a subdivision of $C$ if

- Every simplex in $\sigma(C)$ is contained in a simplex in $C$
- Every simplex in C is the union of finitely many simplices in $\sigma(\mathrm{C})$


A simplicial map from complex $C$ to complex D , is a function mapping vertices of $C$ to $D$ such that all simplices of $C$ are mapped to simplices of $D$


## Asynchronous Computability Theorem (Herilhy and Shavit 93)

A decision task <l, O, $\Delta>$ has a protocol for an asynchronous wait-free model* Iff
There exists a subdivision $\sigma$ of I and a simplicial map $\mu: \sigma(I) \rightarrow O$, such that
It fits $\Delta$ requirements *

Stage 2: Decision making



Red $=$ first person

## Green = second person


$I=\{(0,0),(0,1),(1,0),(1,1)\}$ *
$O=\{(0,0),(1,1)\}$ *

If both parties get 0 , they must both terminate with 0 . Red 0 must map back to red 0 .


## Consider the Quasi-Consensus Problem

Identical to binary consensus problem, but if both are given mixed inputs, either they agree, or green chooses 0 and red chooses 1
(but not vice versa)


The quasi-consensus problem is solvable!

Consensus problem for more than 2 nodes/Two Generals Problem? Generalization of previous argument

K-set agreement problem for more than 2 nodes? Requires Sperner's Lemma
Anonymous Protocols e.g. renaming problem (Output do not depend on person ID)? Variant of the theorem for anonymous protocols.

Other communication primitives? Herlihy and Rajsbaum 94
Decidability of the protocol? Herlihy and Rajsbaum 97
Complexity of the protocol? Hoest and Shavit 97

1. Protocol for asynchronous wait-free model = simplicial map from subdivision of I to O with certain $\Delta$ properties *
2. Binary consensus problem cannot be solved since one cannot construct subdivision + simplicial map due to connectivity property of the map
3. Topological perspective for theory of distributed and concurrent computation (or other branches of computer science...?)


## Thank you



## Colouring

1. A complex is chromatic if

- Each vertex has a colour and no "adjacent" vertices have the same colour

2. A simplicial map is chromatic if

- It also preserves vertex's colours after the map



## Other handwavy definitions

A carrier is the unique smallest simplex in the original complex that contains that simplex in the subdivision complex

A subdivision is chromatic if it is a chromatic complex and for each simplex $S$ in the subdivision, the colours of $S$ is in the set of colours of carrier S

Turns out using a graph is not good enough!
We need DIMENSION to represent clusters of nodes as well.
Simplex is a non-empty finite set
Complex is a collection of simplices closed under containment

- Any subset of a simplex in a complex is also a simplex of the complex


## Asynchronous Computability Theorem (Herilhy and Shavit 93)

A decision task (I, O, $\Delta$ ) has a wait-free protocol using read-write memory

Iff
There exists a subdivision $\sigma$ of I and a simplicial map $\mu: \sigma(I) \rightarrow 0$, such that
$\sigma$ is a chromatic sub-division and
$\mu$ is chromatic simplicial map and
for each simplex $S$ in $\sigma(\mathrm{I}), \mu(\mathrm{S}) \in \Delta($ carrier $(\mathrm{S}, \mathrm{I}))$

Our input complex I looks like this:


Our output complex O looks like this:


Can you guess why we cannot find the required subdivision of the input complex + simplicial map required?

## Similarly:

Simplex = state of a group of people
Subdivision = possible states after running a protocol
Common vertex in two simplexes= person who cannot distinguish two states based on their local information

Simplicial map that fits $\Delta=$ what each person chooses after running the protocol based on their local state

# Simplex = set of mutually connected nodes 

Complex $=$ collection of simplices

> Subdivision = triangulation of a complex

Simplicial map =
mapping vertices of one complex to another while preserving simplexes

